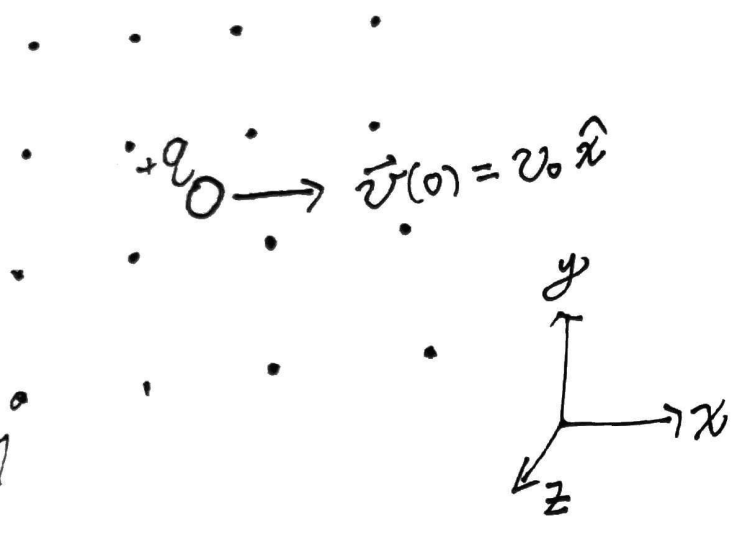


⌊ "Cyclotron motion"

Circular motion of charged particle in uniform B-field.

$$(x, y, z)(t=0) = 0$$



Uniform B-field pointing out of the page. (+z) direction

← Point

← X tail

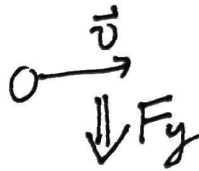
(a) Force at $t=0$?

$$\vec{F} = q (\vec{v} \times \vec{B})$$

$$\begin{matrix} \downarrow & \downarrow \\ v_0 \hat{x} & B \hat{z} \end{matrix}$$

$$= q v_0 B_0 (\hat{x} \times \hat{z})$$

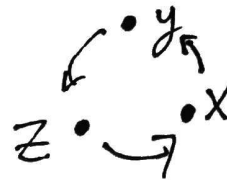
$$= q v_0 B_0 (-\hat{y})$$



Reminder:

$$\hat{x} \times \hat{y} = \hat{z}, \quad \hat{y} \times \hat{z} = \hat{x}, \quad \hat{z} \times \hat{x} = \hat{y}$$

Try it
one



$$\left(\begin{array}{l} \text{If } \vec{a} \times \vec{b} = \vec{c} \\ \Rightarrow \vec{b} \times \vec{a} = -\vec{c} \end{array} \right) \quad \begin{array}{l} -\vec{a} \times \vec{a} \\ \Downarrow \\ \vec{a} \times \vec{a} = 0 \end{array}$$

$$\hat{x} \times \hat{z} = -\hat{z} \times \hat{x} = -\hat{y}$$

(b) Suppose at t_1 , $\vec{v}(t)$.
 What is $\vec{F}(t)$?

$$\vec{F} = q \cancel{|\vec{v}|} B (\cancel{\vec{v}} \times \hat{z})$$

$$= q B (\vec{v} \times \hat{z})$$

$$\vec{v} = v_x \hat{x} + v_y \hat{y} + v_z \hat{z}$$

$$\vec{v} \times \hat{z} = v_x \underbrace{\hat{x} \times \hat{z}}_{-\hat{y}} + v_y \underbrace{\hat{y} \times \hat{z}}_{\hat{x}} + v_z \underbrace{\hat{z} \times \hat{z}}_0$$

$$= -v_x \hat{y} + v_y \hat{x}$$

$$\Rightarrow \vec{F} = (q B v_y) \hat{x} - (q B v_x) \hat{y}$$

$F_z = 0$ ← More generally, $\vec{F} \perp \vec{B}$
 (also $\vec{F} \perp \vec{v}$)

(c) Because $\vec{F} \perp \vec{v}$
 ↳ No work is done

$$W = \vec{F} \cdot \vec{v} = 0$$

Total kinetic energy is const.

$$\parallel mv^2 \Rightarrow \boxed{|\vec{v}| = \text{const.}}$$

$$F_z = 0, \quad (\cancel{v_z(0) \neq 0})$$

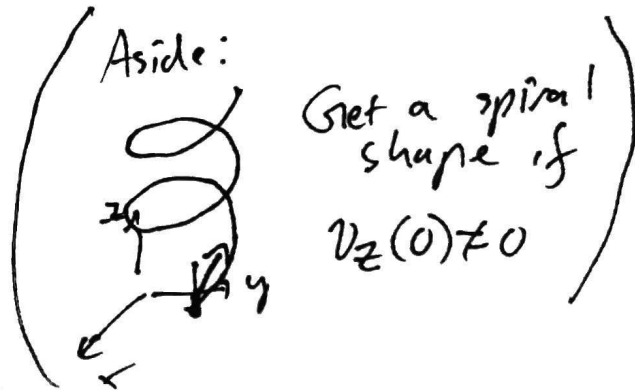
↳ v_z is const

$$F = ma \Rightarrow a_z = 0$$

Initially,

$$v_z = 0$$

$$\Rightarrow v_z = 0 \quad (\forall t) \text{ always}$$



(d) Apply Newton's ~~3rd~~ ^{2nd} Law:

$$\vec{f}(\vec{v}) = \vec{F} = m \vec{a} = m \frac{d}{dt} \vec{v}$$

(Know how to get \vec{F} , \vec{a} in terms of \vec{v})

$$qBv_y = F_x = m \frac{dv_x}{dt}$$

$$-qBv_x = F_y = m \frac{dv_y}{dt}$$

$$(0 = F_z = m \frac{dv_z}{dt})$$

Notice: To relate v_y back to v_x , just have to take derivative:

$$\frac{d}{dt} \left[\frac{dv_x}{dt} \right] = \frac{qB}{m} \frac{dv_y}{dt}$$

$$\frac{d^2}{dt^2} v_x = - \left(\frac{qB}{m} \right)^2 \frac{dv_y}{dt} v_x$$

(Compare: $\ddot{x} = -\omega^2 x$ harmonic motion.)

Coupled ODE

$$\frac{dv_x}{dt} = \left(\frac{qB}{m} \right) v_y$$
$$\frac{dv_y}{dt} = \left(-\frac{qB}{m} \right) v_x$$

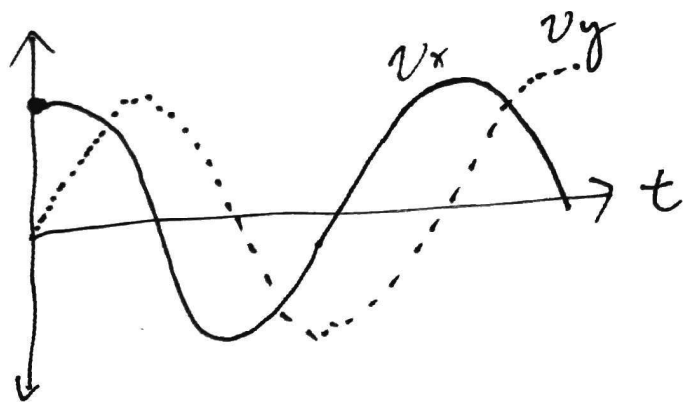
$$\Rightarrow v_x = A \cdot \cos(\omega t)$$
$$\omega = \frac{qB}{m}, A = v_x(0)$$

$$\begin{aligned}
 v_y &= \left(\frac{m}{qB}\right) \frac{dv_x}{dt} \\
 &= \frac{m}{qB} \frac{d}{dt} [v_0 \cos(\omega t)] \\
 &= \frac{m}{qB} \cdot \omega [-\omega v_0 \sin(\omega t)] \\
 &\quad \quad \quad \parallel \\
 &\quad \quad \quad \frac{1}{\omega}
 \end{aligned}$$

$$v_y = -v_0 \sin(\omega t)$$

$$(v_z = 0)$$

$$v_x = v_0 \cos(\omega t)$$



$$\omega = \frac{qB}{m}$$

(e) Integrate to get position

$$x = \int_0^t v_x dt + x(0)$$

$$= \frac{v_0}{\omega} \sin(\omega t)$$

$$(y = \frac{v_0}{\omega} [\cos(\omega t) - 1])$$

$$y = \int_0^t v_y(t') dt' + y(0) = 0$$

$$= \left[\frac{v_0}{\omega} \cos(\omega t)\right]_0^t = \frac{v_0}{\omega} [\cos \omega t - 1]$$

$$\frac{dv_x}{dt} = \frac{qB}{m} v_y$$

$$\frac{d}{dt} \left[\frac{dv_x}{dt} \right] = \frac{d}{dt} \left[\frac{qB}{m} v_y \right]$$

$$\frac{d^2 v_x}{dt^2} = \frac{qB}{m} \frac{dv_y}{dt}$$

← use $\frac{dv_y}{dt} = -\frac{qB}{m} v_x$ ($\phi = \pi/2 \rightarrow \sin$)

$$= \frac{qB}{m} \left(-\frac{qB}{m} v_x \right)$$

$$\frac{d^2}{dt^2} v_x = -\underbrace{\left(\frac{qB}{m} \right)^2}_{\omega^2} v_x$$

Most gen sol:
 $v_x(t) = A \cos(\omega t + \phi)$

v_x could be cos, or sin

$$\frac{d^2}{dt^2} v_x(t) = -\omega^2 v_x(t)$$

$v_x = v_0$ to start with
 \rightarrow pick cos.

$$\Rightarrow \boxed{v_x(t) = \underbrace{v_x(0)}_{v_0} \cdot \cos(\omega t)}$$

$$(f) \quad x(t) = \frac{v_0}{\omega} \sin \omega t$$

$$y(t) = \frac{v_0}{\omega} [\cos \omega t - 1]$$

$$\omega = \frac{qB}{m}$$

"Cyclotron frequency"

Uniform
 \Rightarrow Circular motion
 with radius

$$r = \frac{v_0}{\omega} = \frac{v_0 m}{qB}$$

$\hookrightarrow q, B$ large
 \Rightarrow Fast, tight loops.

$$\omega t = \pi/2 \rightarrow x = \frac{v_0}{\omega}$$

$$y = \frac{v_0}{\omega} [\cos \frac{\pi}{2} - 1]$$

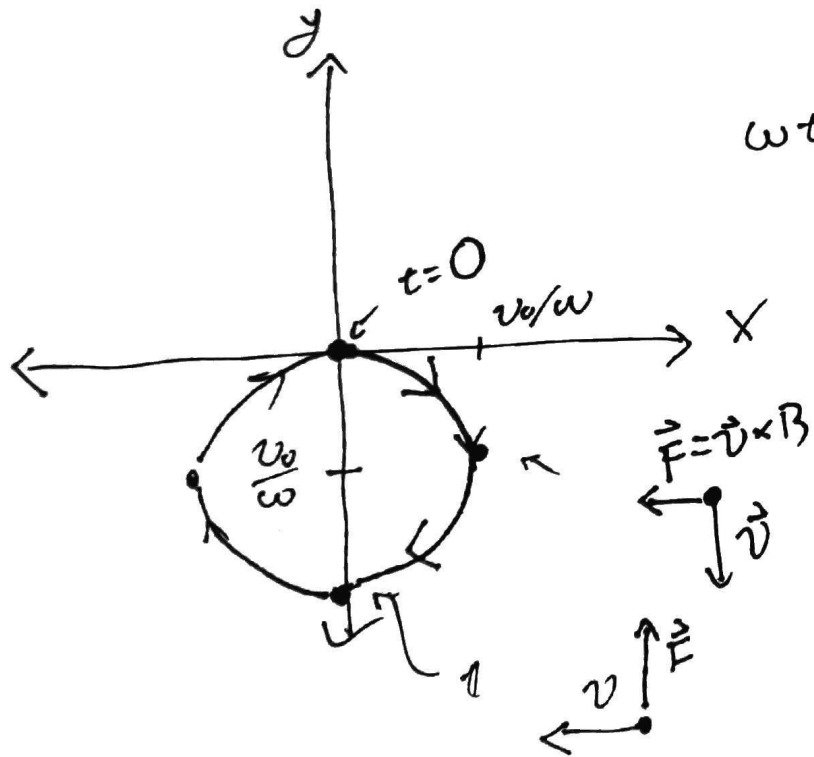
$$= \frac{v_0}{\omega} (-1)$$

v_0 large

\hookrightarrow Large loops.

$$\omega t = \pi \rightarrow x = 0$$

$$y = -2 \frac{v_0}{\omega}$$



* Lesson:

For motion in magnetic field,
 solve for \vec{v} first.